Optimal Data Placement on Networks With Constant Number of Clients

Eric Angel[1], Evripidis Bampis[1], Gerasimos G. Pollatos[*,2], and Vassilis Zissimopoulos[2]

[1] Université d'Évry-Val d'Essone, IBISC CNRS FRE 2873, 523 place des Terrasses, 91000 Évry, France
`{angel,bampis}@ibisc.univ-evry.fr`
[2] Department of Informatics and Telecommunications, University of Athens, Greece
`{gpol,vassilis}@di.uoa.gr`

Abstract. We introduce optimal algorithms for the problems of data placement (DP) and page placement (PP) in networks with a constant number of clients each of which has limited storage availability and issues requests for data objects. The objective for both problems is to efficiently utilize each client's storage (deciding where to place replicas of objects) so that the total incurred access and installation cost over all clients is minimized. In the PP problem an extra constraint on the maximum number of clients served by a single client must be satisfied. Our algorithms solve both problems optimally when all objects have uniform lengths. When objects lengths are non-uniform we also find the optimal solution, albeit a small, asymptotically tight violation of each client's storage size by εl_{max} where l_{max} is the maximum length of the objects and ε some arbitrarily small positive constant. We make no assumption on the underlying topology of the network (metric, ultrametric etc.), thus obtaining the first non-trivial results for non-metric data placement problems.

1 Introduction

Peer-to-peer file sharing networks have become one of the most popular aspects of everyday internet usage. Users from all around the globe interact in an asynchronous manner, benefiting from the availability of the desired content in neighboring or more distant locations. The success of such systems stems from the exploitation of a new resource, different from the traditional bandwidth - related resources, namely the distributed storage. Widespread utilization of this new resource is due to the fact that larger capacities have become cheaper, with significantly smaller data access times. Interacting users, utilize this resource by installing local storage, replicating popular content and then making it available to neighboring users, thus dramatically decreasing bandwidth consumption, needed to access content from the origin servers at which it is available.

A suitable abstract model describing perfectly the aforementioned situation is the *data placement* problem (DP) [1]. Under this model, a set of clients (equivalently users or machines) with an underlying topology is considered and each client has a local amount of storage (cache) installed. Given the set of available objects and the preference that each client has for each object, the objective is to decide a replication scheme, also referred to as a *placement* of objects to local caches so as to minimize the total access cost among all clients and objects. The generalization of this model, under which each client's cache has an upper bound on the number of clients it can serve is known as the *page placement* problem (PP) [14].

It should be noted, that the term replication is used here instead of caching, because under the discussed model, a client cannot change the contents of its local storage without reinvocation of a replication algorithm. On the contrary, the term caching refers to the process of choosing objects to store locally so as to serve requests and use a replacement scheme so as to replace some of them for others on-the-fly according to popularity or other criteria.

Our contributions. We descibe optimal algorithms, combining configurations generation and dynamic programming techniques, for the data placement and page placement problems, when the number of clients is constant. This is a natural variation, interesting from both a theoretical and practical point of view ([3, 4, 7]). Up to now, the only way to tackle these problems, was the 10-approximation algorithm of [2] and the 13-approximation algorithm of [6]), both designed for the general case and both based on rounding the solution of an appropriate linear program. When object lengths are uniform (or equivalently unit) our algorithm finds the optimum solution in polynomial time. When object lengths are non-uniform, our algorithm returns an optimum solution which violates the capacities of the clients' caches by a small, asymptotically tight additive factor. Our results, summarized in table 1, can be modified to handle various extensions of the basic problems such as the connected data placement problem ([2]) where object updates are frequent and consistency of all replicas of each object has to be guaranteed and the k-median variant of DP where bounds are imposed on the number of maximum replicas allowed for each object. Furthermore, our results are applicable with uniform and non-uniform object lengths and can be employed independently of the underlying topology of the network, thus giving the first non-trivial results for non-metric DP problems.

Related work. The study for the data placement problem over an arbitrary network where all inter-client distances form a metric was initiated in [1] where the authors proved that the problem in the case of objects of uniform length is MAXSNP-hard. They also devised a polynomial 20.5-approximation algorithm based on the rounding of the optimal solution of a suitable linear program. In the case of objects of non-uniform length, the authors proved that the problem of deciding whether an instance admits a solution is NP-complete and provided a polynomial 20.5-approximation algorithm that produces a solution at which the capacity of each client's cache exceeds its capacity in the optimum solution by

	Known results		In this paper	
	arbitrary M		fixed M	
	metric	no metric	metric	no metric
uniform lengths DP	10-approx [1, 2, 6]	-	optimal	
non-uniform lengths DP	10-approx with blow-up $l_{\max}$ [2]	-	optimal with blow-up εl_{max}	
page placement	13-approx [6] *	-	optimal with blow-up** εl_{max}	
connected DP	14-approx [2]	-	optimal	
k-median DP	10-approx [1, 2]	-	optimal	

Table 1. The main known results on data placement problems (*non-uniform lengths with constant blow-up on clients and cache capacities, **non-uniform lengths with constant blow-up on cache capacities only).

at most the length of the largest object. The approximation ratio for unit-sized objects was later improved to 10 in [16] and [2].

Various previous works have also considered variants of the data placement problem in terms of the underlying topology. In [13] the authors consider the case of distances in the underlying topologies that form an ultrametric, i.e. are non-negative, symmetric and satisfy the *strong* triangle inequality, that is $d(i, j) \leq \max\{d(i, k), d(k, j)\}$ for clients i, j, k. The authors consider a simple hierarchical network consisting of three distances between the clients and devise a polynomial algorithm for the case of unit-sized objects by transforming it to a capacitated transportation problem [5]. For the case of general ultrametrics, an optimal polynomial algorithm is given in [9] based on a reduction to the min-cost flow problem.

The *page-placement problem* is an important generalization of the data placement and was proposed and studied in [14]. In this problem, each client has an extra constraint on the number of other clients it can serve, apart from the constraint on the capacity of its cache. In [14], the authors give 5-approximation algorithm for the problem which violates both client and cache capacity constraints by a logarithmic factor at most. In [6], the logarithmic violation of both capacity constraints was improved to constant with a 13-approximation algorithm. Finally, in [11] and [15] a game-theoretic aspect of the data placement problem is studied, where clients are considered to be selfish agents. In both works, algorithms are provided which stabilize clients in equilibrium placements.

All previous results capture situations where write requests are rarely or never issued for the objects. In [2] the authors consider the case when write requests are common and formulate the *connected data placement* problem, in which it is required that all replicas of an object o are connected via a Steiner tree T_o to a root r_o, which can later be used as a multicast tree. The objective is the minimization of the total incurred access cost and the cost of building the Steiner tree. A 14-approximation algorithm for the problem is given in [2]. This problem is a generalization of the *connected facility location problem* for which the best known approximation ratio is 8.55 [17].

In section 2 we formally define the DP problem and introduce appropriate notation. In section 3 we present our main results for the DP problem, whereas in section 4 we present an algorithm for the page placement problem and also briefly discuss modifications for the other extensions.

2 Problem definition

The data placement problem we consider in this paper is identical to the one in [1] and is abstracted as follows[3]. There is a network $\mathcal{N}$ consisting of a set $\mathcal{M}$ of $M = |\mathcal{M}|$ users (clients) and a universe $\mathcal{O}$ of $N = |\mathcal{O}|$ objects. In what follows we use the terms user and machine interchangeably. Each object $o \in \mathcal{O}$ has length l_o and each user $j \in \mathcal{M}$ has a local capacity C_j for the storage of objects. The distance between the users can be represented by a distance matrix D (not necessarily symmetric) where d_{ij} denotes the distance from j to i. The matrix D models the underlying topology. We do not assume any restrictions (e.g. metric) on the distances. Each user i requests access to a set of objects $R_i \subseteq \mathcal{O}$, namely its *request set*. For each object o in its request set, client i has a *demand* of access $w_{io} > 0$. This demand can be interpreted as the frequency under which user i requests object o. The subset P_i of its request set, that i chooses to replicate locally is referred to as its *placement*. Obviously, $|P_i| \leq C_i$ for unit-sized objects. We assume an installation cost f_i^o for each object o and each cache i. The objective is to choose placements of objects for every client such as the total induced access and installation costs for all objects and all clients is minimized. In the following, we will assume without loss of generality that each object $o \in \mathcal{O}$ is requested by at least one user.

We define a *configuration* $c \subseteq \mathcal{M}$ as a (non empty) subset of the M machines. Thus, we have $2^M - 1$ distinct configurations and we denote by $\mathcal{C}$ the set of all configurations. For a configuration $c \in \mathcal{C}$ and a user j we say that j *is used with respect to* c, denoted by $j \in c$, if the configuration c contains j's cache, i.e. machine $m_j \in c$. It will be also convenient to introduce the following notation: $p_{cj} = 1$ if $j \in c$, and $p_{cj} = 0$ otherwise. For an object o, we define a *c-placement* with respect to o, as a placement of object o to the machines belonging to c.

Introducing binary variables x_{oc} to denote whether we choose or not the *c*-placement with respect to o, we can formulate our problem as an integer linear program, denoted by ILP in the sequel, in the following way:

$$
\begin{aligned}
\text{minimize} \quad & \sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} cost_{oc}\, x_{oc} \\
\text{subject to} \quad & \sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} l_o\, p_{cj}\, x_{oc} \leq C_j \quad j \in \mathcal{M} \\
& \sum_{c \in \mathcal{C}} x_{oc} = 1 \qquad o \in \mathcal{O} \\
& x_{oc} \in \{0,1\} \qquad o \in \mathcal{O},\ c \in \mathcal{C}
\end{aligned}
\tag{ILP}
$$

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[3] In [2] a seemingly different but essentially equivalent formulation of the problem is described.

where $cost_{oc}$ is the total cost induced if configuration c is used for the placement of object o, that is $cost_{oc} = \sum_{j \in \mathcal{M}} (1 - p_{cj}) \, w_{jo} \, l_o \, d_j(c) + \sum_{j \in \mathcal{M}} p_{cj} \, f_j^o$, with $d_j(c) = \min_{j' \, : \, p_{cj'}=1} d_{j'j}$ the nearest distance at which client j can access object o under configuration c. The first set of constraints essentially states that the set of objects that each user replicates must not violate the user's cache constraint, while the second set states that for each object exactly one configuration should be chosen. In what follows we denote by OPT the optimum solution of the previous program.

Note that the problem, as defined above does not always admit a feasible solution. In order to avoid trivial cases of infeasibility we assume in the sequel that $\sum_{i \in \mathcal{M}} C_i \leq \sum_{o \in \mathcal{O}} l_o$ which essentially states that all clients can collectively store the union of the requested objects. Other works ([13, 9]) assume existense of a distant server, that is, a user holding as a fixed placement the universe of objects, which essentially tackles the problem of infeasibility. For the case of uniform sized objects, this assumption has no effect in the problem's hardness since the hardness result of Baev et al. [1] also holds in this case. However, in the case of non-uniform sized objects, their result does not hold immediately, since it relies on the fact that it is sometimes not possible to find any feasible solution. When a distant server exists, any instance always admits a feasible solution. Nevertheless, their proof of non-approximability can be adapted and thus the following result can be obtained. Due to space limitations, we defer the details of the proof to the full version of this paper.

Proposition 1. *For any polynomial time computable function $\alpha(N)$, the data placement problem with non uniform object lengths and without any augmentation in cache capacities, cannot be approximated within a factor of $\alpha(N)$, unless* **P=NP***.*

The problem can also be stated as a constrained shortest path problem as follows: we introduce a node for each binary variable x_{oc} and two nodes s and t and connect them as follows: for each o_i, $1 \leq i \leq N - 1$ we connect the node that represents $x_{o_i c}$ with every node that represents $x_{o_{i+1} c}$ for all c. Furthermore we connect node s with nodes $x_{o_1 c}$ and node t with nodes $x_{o_N c}$ for all c. At each edge $(x_{o_i c}, x_{o_{i+1} c'})$ we assign a weight equal to $cost_{o_i c}$ for $1 \leq i \leq N - 1$. Edges $(x_{o_N c}, t)$ have weight $cost_{o_N c}$ and edges $(s, x_{o_1 c})$ have a weight of 0. The objective is to find the shortest path between nodes s and t while respecting cache capacity constraints on each node. These constraints are assigned to each node $x_{o_i c}$ by simply summing up for each client contained in configuration c the current cache contents up to object o_i. This constrained shortest path problem can be solved using dynamic programming. It leads to the algorithm presented in the next section.

3 Constant number of clients

In this section we focus in the case where the number of clients in the network (i.e. users) is a constant. To the best of our knowledge these are the first results for

this natural variation. We show that the data placement problem can be solved optimally in polynomial time when all objects are unit-sized. When objects have different sizes we are still able to solve the problem optimally, with only a small and asymptotically tight violation of the cache capacities.

3.1 Uniform length objects

Let us define an available cache vector $r = (r_1, r_2, \ldots, r_M)$, where r_j denotes the current space size available on cache of user j, for $1 \leq j \leq M$. For $1 \leq k \leq N$, let us denote by $f_k(r)$ the cost associated with the optimal way of placing objects $o_1, \ldots, o_k$ on the clients' caches, assuming that the current available cache vector is r. For any configuration c, we denote by $\delta_c = (\delta_c^1, \ldots, \delta_c^M)$ its machine-profile vector, with $\delta_c^i = 1$ if configuration c uses machine m_i, and $\delta_c^i = 0$ otherwise. We assume in this section that all lengths satisfy $l_o = 1$, but the following recurrence holds for the general case and it will be also used in the next section. One has

$$f_k(r) = \min_{c \,:\, r - l_{o_k} \delta_c \geq 0} (cost_{o_k c} + f_{k-1}(r - l_{o_k} \delta_c)),$$

with $f_0(r) = 0$ for any r. Finding the optimum cost to ILP reduces to the computation of $f_N(r)$ with $r = (C_1, C_2, \ldots C_M)$.

Theorem 1. *The non-metric data placement problem with uniform length objects and a fixed number of clients can be solved optimally in polynomial time.*

Proof. By using standard techniques (see for example [8]), the above recurrence leads to an efficient dynamic programming algorithm to obtain the optimal cost and solution of ILP. The cache vectors r can take values from a set of size $\prod_{j=1}^{M} C_j \leq C_{max}^M$ where C_{max} is the maximum cache size. Assuming the values $f_k(r)$ are stored in an array and computed from $k = 1$ to $k = N$, then for each r the time needed to compute $f_k(r)$ is $O(2^M)$, i.e. a constant time, since at most 2^M configurations need to be checked. The total time complexity is therefore $O(N2^M C_{max}^M)$. Notice that since objects are unit-sized, i.e. $l_o = 1$, $\forall o \in \mathcal{O}$, we can assume without loss of generality that for any capacity we have that $C_j \leq N$. If it is not the case, by changing this capacity to $C_j := N$, we obtain an equivalent instance because in the model considered, a client has no incentive to replicate any distinct object twice, since this would have no effect in the total access cost. Finally, the computation time becomes $O(N^{M+1})$. $\square$

3.2 Non-uniform length objects

The previous dynamic programming algorithm is in fact pseudo-polynomial, since the complexity $O(N^M C_{max}^M)$ depends on the maximum cache size C_{max}. In the case of unit-sized objects we are able to bound C_{max} by the total number of objects and thus obtain a polynomial time algorithm. In the case of objects of arbitrary length the bound $C_{max} \leq N$ does not hold and the algorithm remains pseudo-polynomial.

Algorithm 1: DP-NU($\mathcal{M}, \mathcal{O}, \varepsilon$)
---
1 $\alpha \leftarrow (\varepsilon l_{max})/N$;
   // update object lengths
2 foreach $o \in \mathcal{O}$ **do**
3 $l'_o \leftarrow \lfloor l_o/\alpha \rfloor$;
   // update cache sizes
4 foreach $j \in \mathcal{M}$ **do**
5 $C'_j \leftarrow \lfloor C_j\alpha \rfloor$;
   // use updated lengths and cache sizes with dynamic programming
6 $OPT_\alpha \leftarrow$ optimum solution of ILP$_\alpha$;
7 Output OPT_α;

In what follows, we show how to design a polynomial time algorithm in the case of arbitrary-sized objects. We let $\alpha = \varepsilon l_{max}/N$ where ε is an arbitrarily small positive constant and modify the object lengths and cache sizes appropriately. To compute a solution we use algorithm 1 where ILP$_\alpha$ denotes the integer linear program obtained from ILP by using length l'_o (resp. cache C'_j) instead of l_o (resp. C_j) for all objects o and clients j.

Notice however that the cost function in ILP$_\alpha$ is the same as in ILP, i.e. the costs $cost_{oc} = \sum_{j \in \mathcal{M}}(1 - p_{cj})\, w_{jo}\, l_o\, d_j(c) + \sum_{j \in \mathcal{M}} p_{cj}\, f^o_j$ are calculated by using the initial lengths l_o. We have the following lemma.

Lemma 1. *Given an $\alpha > 0$, any solution x for ILP is a solution for ILP$_\alpha$.*

Proof. Let x be a solution of ILP. One has, $\forall j \in \mathcal{M}$,

$$\sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} \left\lfloor \frac{l_o}{\alpha} \right\rfloor p_{cj}\, x_{oc} \leq \sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} \left\lfloor \frac{l_o}{\alpha}\, p_{cj}\, x_{oc} \right\rfloor \leq \left\lfloor \sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} \frac{l_o}{\alpha}\, p_{cj}\, x_{oc} \right\rfloor \leq \left\lfloor \frac{C_j}{\alpha} \right\rfloor,$$
(1)

where the first inequality comes from the fact that p_{cj} and x_{oc} are integers, the second inequality is a standard one, and the last inequality comes from $\sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} l_o\, p_{cj}\, x_{oc} \leq C_j$ since x is a feasible solution of ILP. Therefore, x satisfies $\sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} l'_o\, p_{cj}\, x_{oc} \leq C'_j$, and x is a feasible solution of ILP$_\alpha$. $\quad\square$

From the above lemma, we can immediately conclude that if ILP$_\alpha$ has no solutions, then the same holds for ILP. However, if ILP has no feasible solutions, ILP$_\alpha$ could have feasible solutions. In the following, we assume that ILP admits at least one feasible solution, in order to be able to define an optimal solution denoted by OPT.

Lemma 2. *The algorithm DP-NU($\mathcal{M}, \mathcal{O}$) returns an optimal solution for ILP using εl_{max} blow-up in time polynomial in N and $1/\varepsilon$, where ε is an arbitrarily small positive constant and l_{max} is the length of the largest object.*

Proof. First, notice that by Lemma 1 the cost of the solution OPT_α is not greater than the cost of the solution OPT. Furthermore, we have that

$$\sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} \left\lfloor \frac{l_o}{\alpha} \right\rfloor p_{cj}\, x_{oc} \geq \sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} \left(\frac{l_o}{\alpha} - 1 \right) p_{cj}\, x_{oc} \geq \sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} \frac{l_o}{\alpha} p_{cj}\, x_{oc} - N$$

which becomes

$$\sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} l_o\, p_{cj}\, x_{oc} \leq \alpha \sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} \left\lfloor \frac{l_o}{\alpha} \right\rfloor p_{cj}\, x_{oc} + \alpha\, N$$

$$\leq \alpha \left\lfloor \frac{C_j}{\alpha} \right\rfloor + N\,\alpha \leq C_j + N\,\alpha \quad \text{(by using inequality (1))}$$

Putting $\alpha = \varepsilon l_{max}/N$ we get for the initial instance

$$\sum_{o \in \mathcal{O}} \sum_{c \in \mathcal{C}} l_o\, p_{cj}\, x_{oc} \leq C_j + \varepsilon l_{max} \tag{2}$$

thus, each cache size is violated by at most εl_{max}.

For the complexity, notice that for any user j's cache, we can assume without loss of generality that $C_j \leq N l_{max}$. If it is not the case, by changing the capacity to $C_j := N l_{max}$, we obtain an equivalent instance because in the model considered, a client has no incentive to replicate any distinct object twice, since this would have no effect in the total access cost. We have therefore,

$$C'_j = \left\lfloor \frac{C_j}{\alpha} \right\rfloor \leq \frac{C_j}{\alpha} \leq \frac{N l_{max}}{\alpha} \leq \frac{N^2}{\varepsilon}.$$

Finally, we obtain $C'_{max} = \max_{j \in \mathcal{M}} C'_j \leq N^2/\varepsilon$ and by a similar analysis as in theorem 1, the complexity of $O(N 2^M C_{max}^M)$ becomes $O(N^{2M+1} \varepsilon^{-M})$. Notice that if α is large enough, some lengths $\lfloor l_o/\alpha \rfloor$ can become equal to zero. In that case, the dynamic programming algorithm can be accelerated for such objects, since an optimal placement is to put them on each machine. □

Using Lemma 2 we obtain the following theorem.

Theorem 2. *The non-metric data placement problem, with non-uniform object lengths and a fixed number of clients, can be solved optimally in polynomial time using εl_{max} blow-up on the machines' capacity, where ε is an arbitrarily small positive constant and l_{max} is the length of the largest object.*

The εl_{max} blow-up stated in the previous theorem is asymptotically tight. In order to clarify this, consider an instance with N objects and two clients M_1 and M_2. The lengths of the objects are $l_i = (1 - \delta)/N$ for $i = 1, \ldots, N - 1$ and $l_N = l_{max} = 1/\epsilon$ where $0 < \epsilon < 1$ and $0 < \delta < 1$. The cache capacities of the clients are $C_1 = \epsilon l_{max} = 1$ for M_1 and $C_2 = 1/\epsilon$ for M_2. All installation costs are 0. Client M_1 has a demand equal to 1 for the first $N - 1$ objects and

no demand for object N. Client M_2 has also a demand of 1 for the first $N-1$ objects and a demand of N for the N-th object. In the optimum solution OPT, M_1 replicates all the $(N-1)$ objects and M_2 replicates only object N. When our algorithm is employed, the lengths of objects i, $1 \leq i \leq N-1$ become $l_i' = \lfloor l_i/\alpha \rfloor = \lfloor 1-\delta \rfloor = 0$. The length of the N-th object becomes $l_{\max}' = \lfloor N/\epsilon \rfloor$ while the cache sizes become $C_1' = \lfloor 1/\alpha \rfloor = N$ and $C_2' = \lfloor N/\epsilon \rfloor$. In the optimum solution OPT_α client M_1 will again choose to replicate the $(N-1)$ objects it has demand for, but client M_2 can now choose all N objects. After restoring the original object lengths and capacities, the total blow-up is only due to M_2 and is equal to $(N-1)((1-\delta)/N)$. Choosing $\delta = 1/(N-1)$ we get $1 - 2/N$ the limit of which is $1 = \epsilon \cdot \frac{1}{\epsilon} = \epsilon \cdot l_{\max}$, as N approaches infinity.

4 The page placement problem

In the page placement problem, there are bounds imposed on the number of clients that can connect to a specified client's cache in order to access objects. We denote by k_j the maximum number of users that can access a given user j's cache. If the same user access cache j for different objects it is counted only once. Clearly, in this problem a client requesting an object can not always use the nearest machine which replicates that object to access it.

We need to introduce some terminology and notations. Let us define an available load vector $t = (t_1, t_2, \ldots, t_M)$, where t_j denotes k_j minus the current number of users connected to the cache j. Notice that the number of load vectors is bounded by $\prod_{j=1}^{M}(k_j + 1) \leq (M+1)^M$. For any configuration c, we denote as before by δ_c its machine-profile vector, i.e. for $1 \leq i \leq M$, $\delta_c^i = 1$ if configuration c uses machine m_i, and $\delta_c^i = 0$ otherwise.

Given an object o and a configuration c, a c-placement is a placement such that a machine m receives the object o if and only if $m \in c$. In a c-placement, the machines outside c need a way to access the object o they are requesting. We call such a way a *connection pattern* ρ with respect to the configuration c, and we denote by Φ_c the set of all such possible connection patterns. Given $\rho \in \Phi_c$, for all $j \notin c$ and $i \in c$, we put $\rho_{ij} = 1$ if user j access object o from user i, and $\rho_{ij} = 0$ otherwise. Moreover, for all $j \in c$ and i we have $\rho_{ij} = 0$. Notice that $|\Phi_c|$ is bounded by $|c|^{M-|c|} \leq M^M$. Finally, we define a *history pattern* s in the following way: $s_{ij} = 1$ if machine m_j has previously used machine m_i to access an object, and $s_{ij} = 0$ otherwise. The number of history patterns is equal to $2^{M(M-1)/2}$. Given ρ and s we denote by $s \vee \rho$ the updated history pattern taking into account the current connection pattern ρ. The updated pattern can be obtained by performing a logical *or* between ρ and s, i.e. $(s \vee \rho)_{ij} = s_{ij} \vee \rho_{ij}$.

For a connection pattern $\rho \in \rho_c$ and a history pattern s, we denote by $\Delta_{\rho,s} = (\Delta_{\rho,s}^i)_{i=1}^M$ the vector which indicates for each machine m_i the number of machines which are connected to m_i for the first time. Such a vector can be obtained in the following way: for $1 \leq i \leq M$, one has $\Delta_{\rho,s}^i = \sum_{j=1}^{M} \rho_{ij}(1 - s_{ij})$. Finally, we define $cost_{o,c,\rho} = \sum_{i,j \in \mathcal{M}} d_{ij} w_{jo} l_o \rho_{ij} + \sum_{i \in c} f_i^o$.

For $1 \leq k \leq N$, let us denote by $f_k(r, t, s)$ the cost associated with the optimal way of placing objects $o_1, \ldots, o_k$ on the clients' caches, assuming that the current available cache vector, load vector and access vector are respectively r, t, s. One has

$$f_k(r, t, s) = \min_{\substack{C \in \mathcal{C}: \\ r - l_k \delta_c \geq 0}} \min_{\substack{\rho \in \rho_c: \\ t - \Delta_{\rho, s} \geq 0}} \left(cost_{o_k, c, \rho} + f_{k-1}(r - l_{o_k} \delta_c, \, t - \Delta_{\rho, s}, \, s \vee \rho) \right),$$

with $f_0(r, t, s) = 0$ for any r, t, s.

Theorem 3. *The non-metric page placement problem with uniform length objects and a fixed number of clients can be solved optimally in polynomial time.*

Proof. Finding the optimum cost to the problem reduces to the computation of $f_N(r, t, s)$ with $r = (C_1, \ldots C_M)$, $t = (k_1, \ldots, k_M)$ and $s = (0, \ldots 0)$. The complexity for computing $f_k(r, s, t)$ is $O(2^M M^M M)$, and there are at most $NC_{max}^M M^M 2^{M(M-1)/2}$ (r, s, t) triplets. As in section 3 (Theorem 1), we can assume that $C_{max} \leq N$ and obtain an overall complexity of $O(N^{M+1})$. $\qquad \square$

For the non uniform case, the same recurrence relation holds, and using a similar technique and analysis as in section 3.2 (not repeated here due to space limitations) the complexity becomes $O(N^{2M+1} \varepsilon^{-M})$ and we obtain the following result:

Theorem 4. *The non-metric page placement problem with non-uniform object lengths and a fixed number of clients, can be solved optimally in polynomial time using εl_{max} blow-up on the machines' capacity, where ε is an arbitrarily small positive constant and l_{max} is the length of the largest object.*

5 Concluding Remarks

In this paper, we addressed the problem of replicating data over a constant number of network clients and designed optimal algorithms via utilization of the notion of configurations. If all data objects are equal in size, our algorithm finds in polynomial time the optimum solution. When lengths of objects differ, a small violation of each client's cache capacity constraint is enough, so as to be able to find the optimum solution.

Our technique constitutes a general framework that can also be used for solving optimally various common extensions of the problem such as: (a) the k-median variant in which an upper bound k_o is imposed on the number of copies of each object o that can be replicated in the network and (b) the connected data placement problem [2], where apart from placing objects, all clients holding replicas of the same object should also be innterconnected via a directed Steiner tree. Furthermore our technique can be applied for other variants of data placement for example the fault tolerant data placement (derived from the fault-tolerant facility location problem [18]) where each client can be served by a given number of machines and the cost is obtained by summing the costs of

access with respect to those machines. We defer the details for these and other extensions, due to space limitations, for the full version of this paper.

The proposed algorithms remain polynomial independently of any metric. An important aspect of further research is the modification of the described algorithm so as to be able to handle extensions involving payments. In such extensions, apart from object preferences, a client also has a budget to spend and pay other clients to convince them to replicate certain objects.

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